

Functional view and Data flow

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Functions interactions

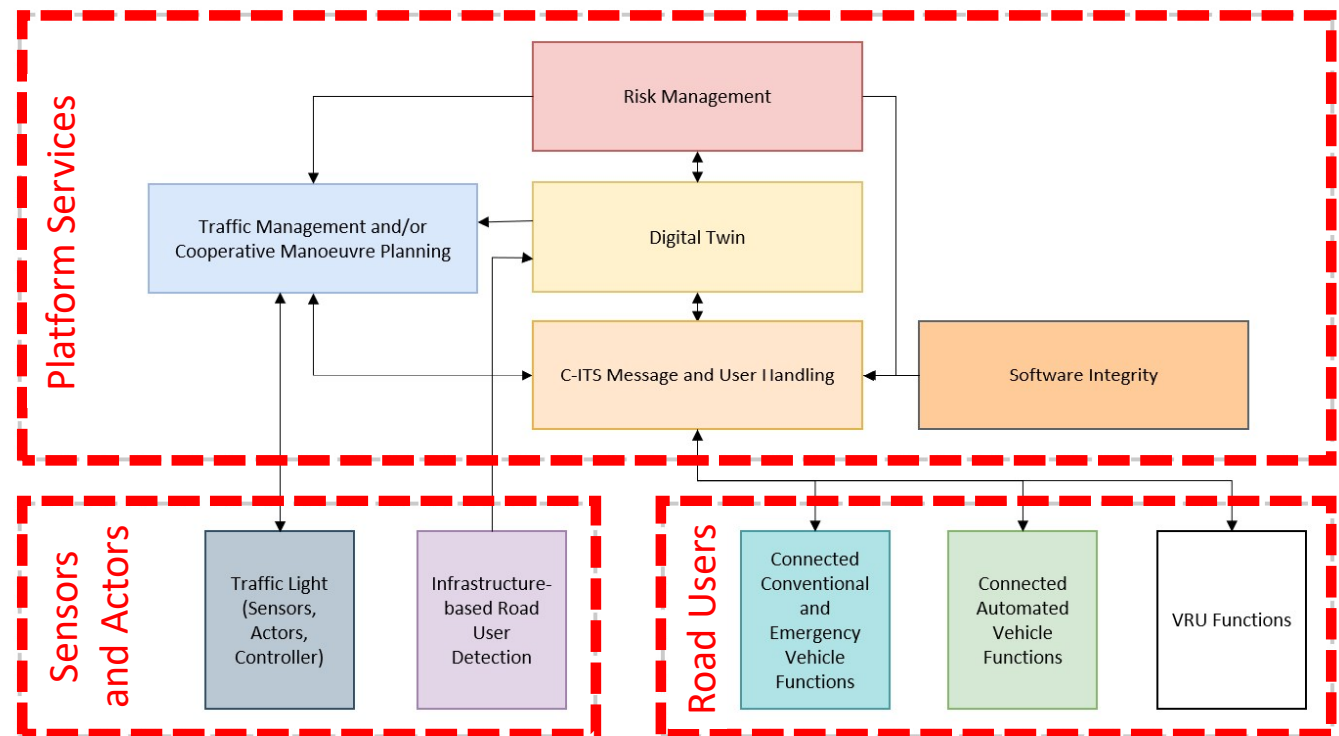
🔗 Interaction between the different PoDIUM functions

🔗 Functional view

- High level common architecture
- Each UC is particularizing this architecture based on its requirements

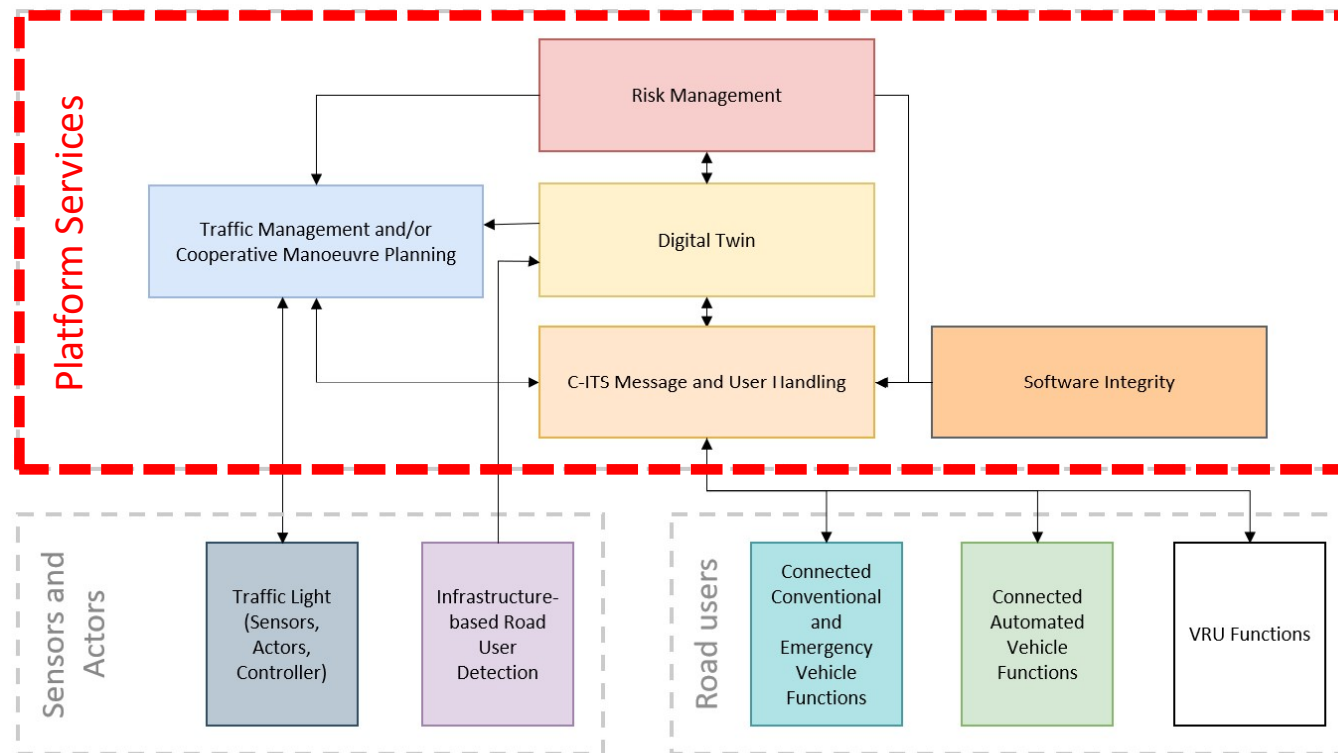
🔗 Three major blocks:

- Platform Services
- Sensors and Actors
- Road Users



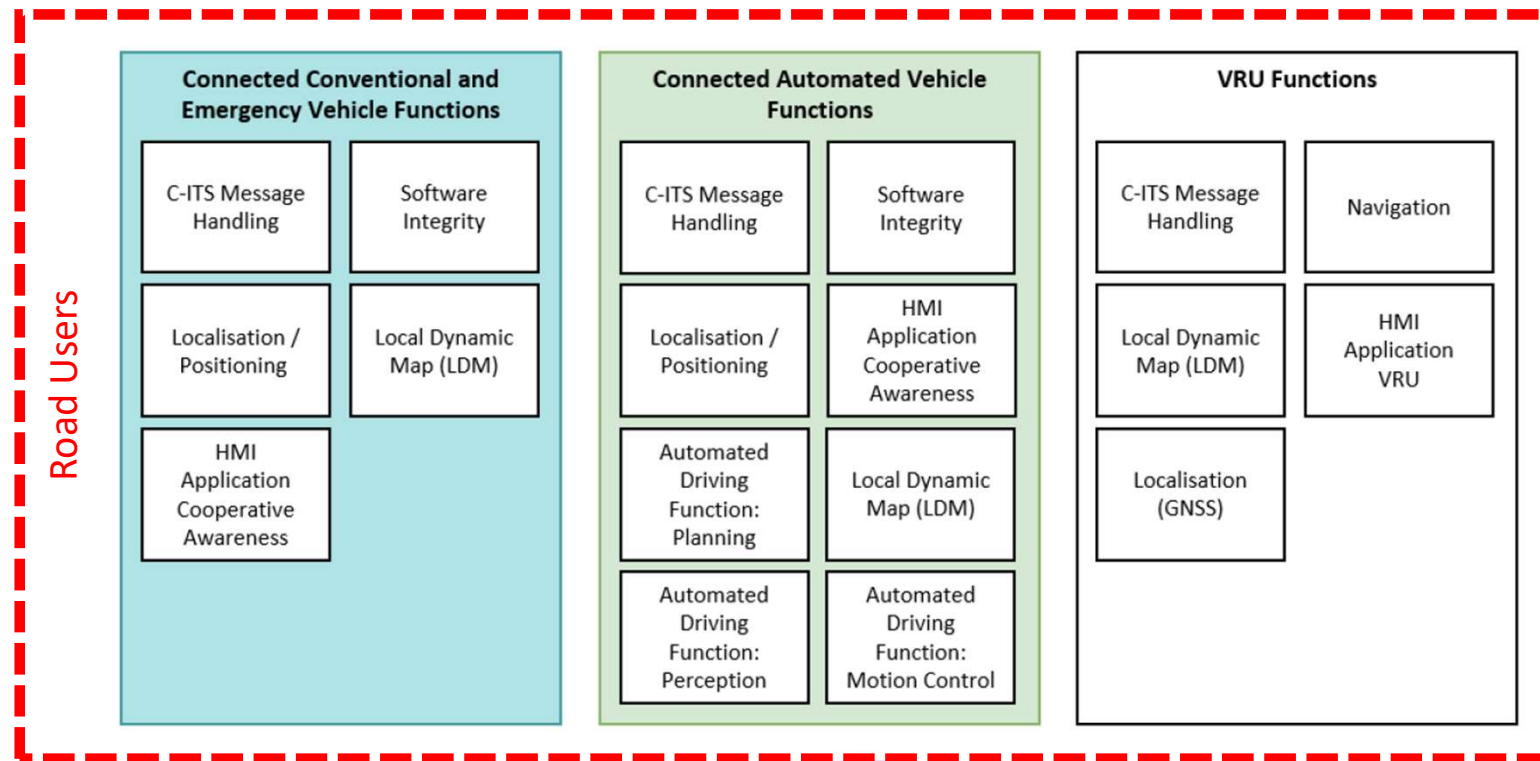
Functions interactions

Platform Services



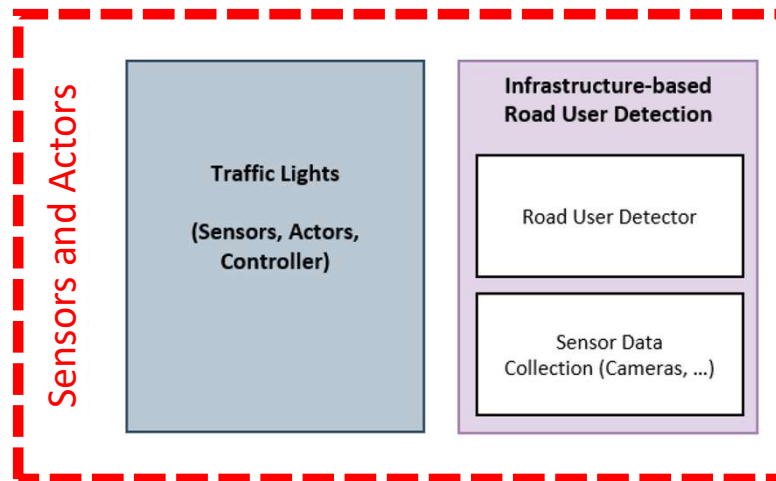
Functions interactions

Road Users



Functions interactions

Sensors and Actors



Data flow

• Standard-oriented approach used by the project:

- Many data messages defined by ETSI standard
- In some cases, there is a need of extending the standard

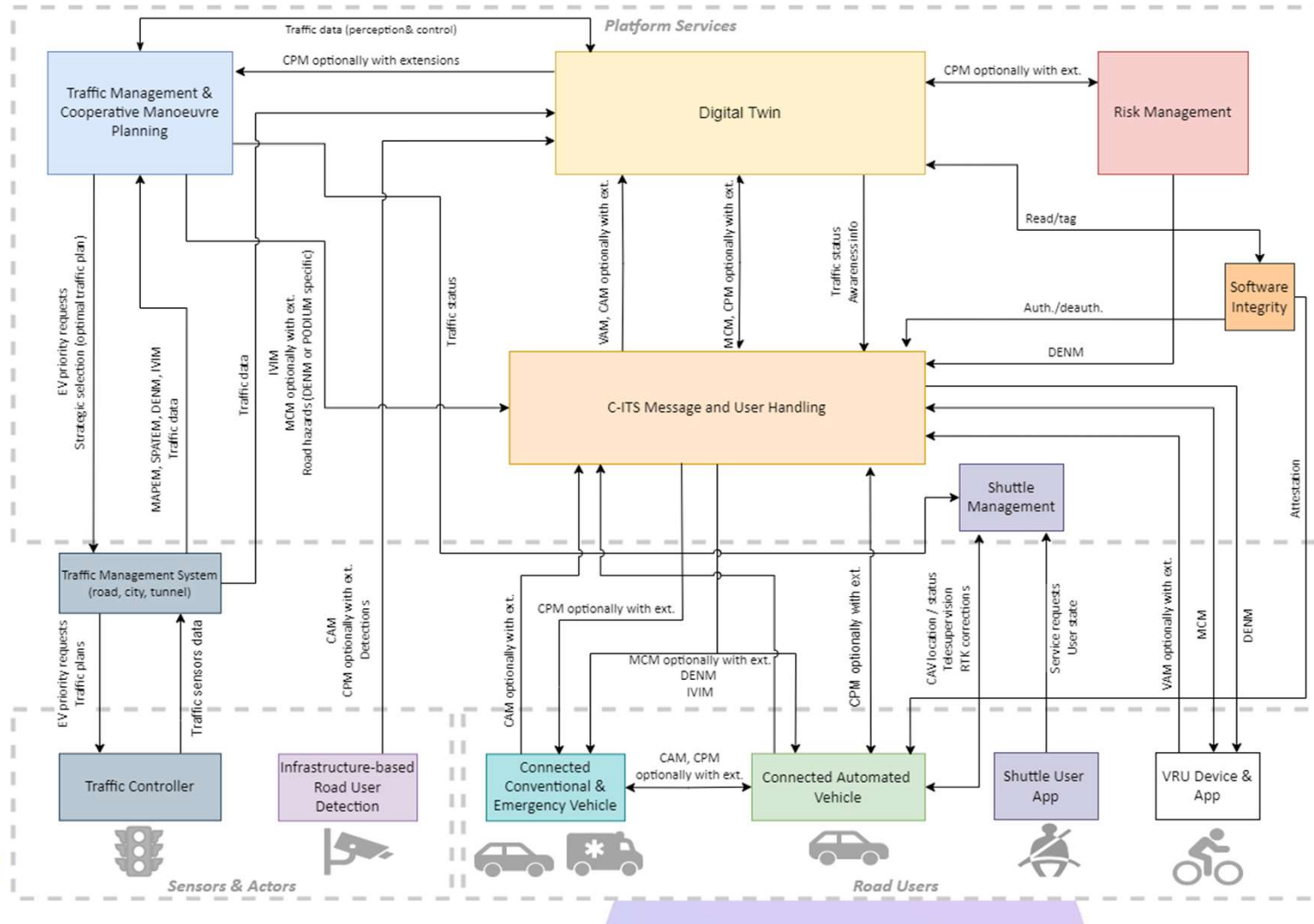
• Semantic interoperability aspects:

- Issues when we are proposing a deviation from the standard:
 - Motivation
 - Possible impact
 - Mitigation strategy

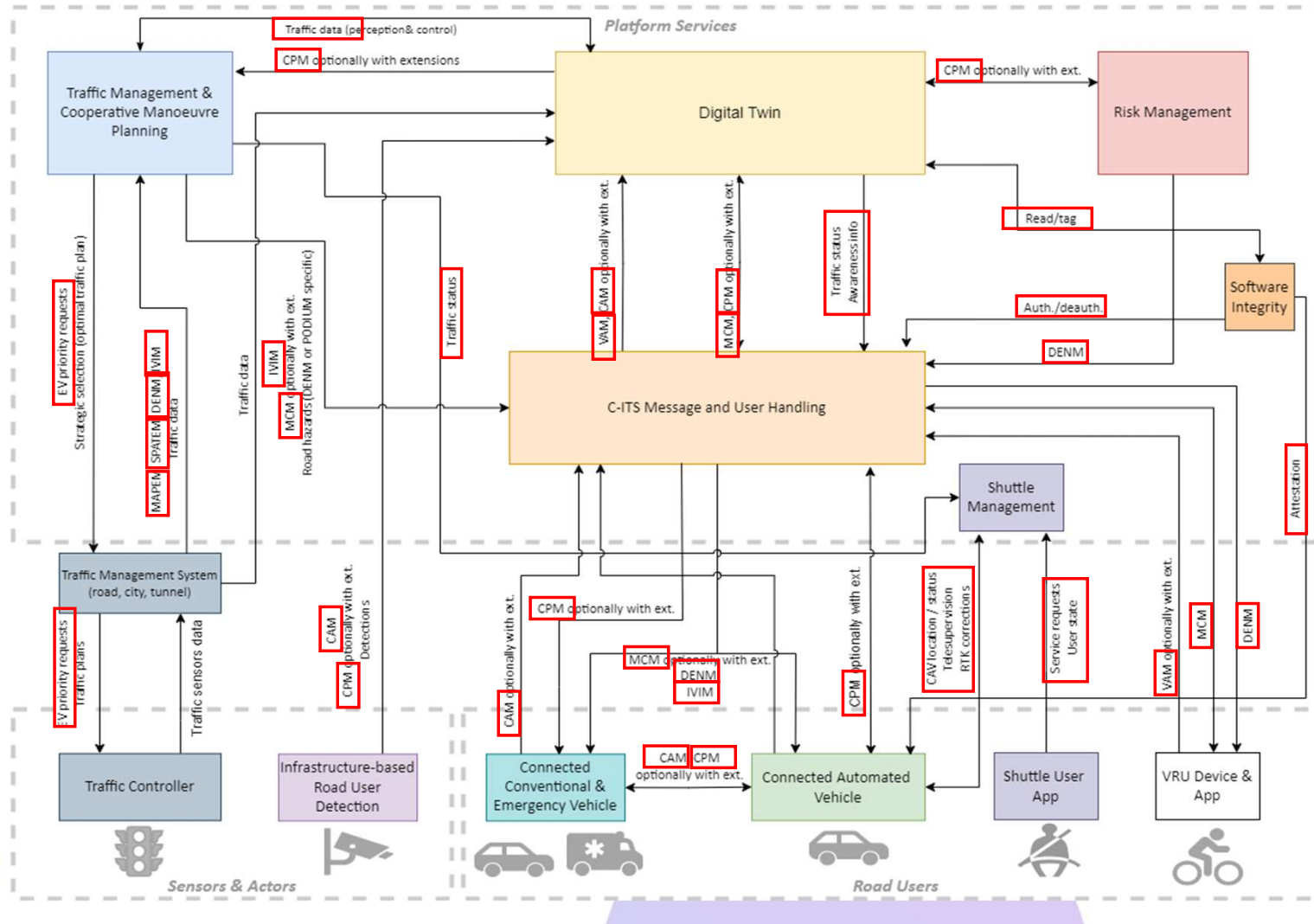
• Data View ⇒ common data management architecture

- Global picture of the management of information within the PoDIUM architecture
- Inspired by the previous functional view
- Each UC is particularizing this architecture based on its requirements

Data flow



Data flow



- CAM** Cooperative Awareness Message
- CPM** Cooperative Perception Message
- DENM** Decentralized Environmental Notification Message
- IVIM** In-vehicle Information Message
- MCM** Manoeuvre Coordination Message
- VAM** VRUs Awareness Message
- MAPEM** MAP Extended Message
- SPATEM** Signal Phase and Timing Extended Message
- OTHERS** EV priority requests
Traffic information
Software integrity
Shuttle management



Thank you!



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PoDIUM Project



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